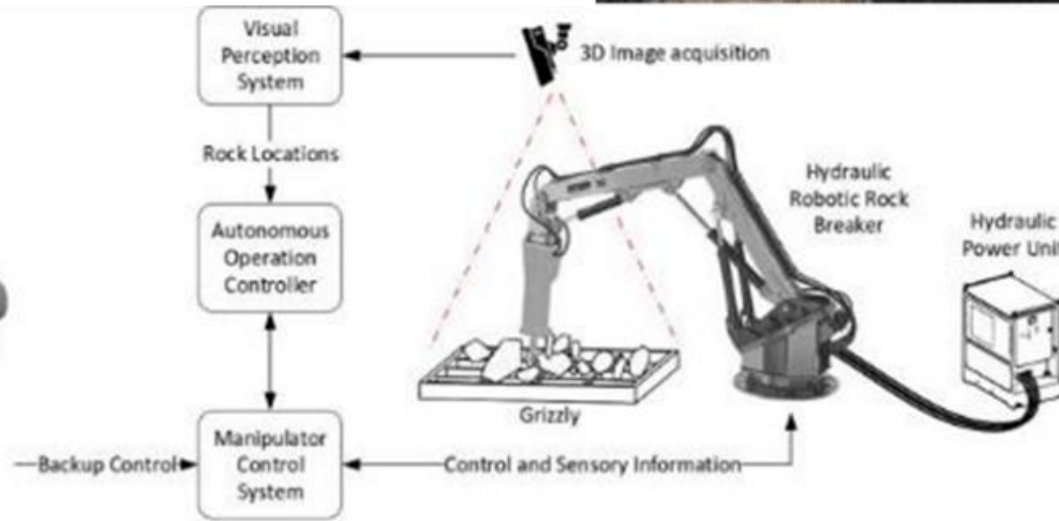




Introduction slides 28.10.2025

AI Powered Autonomous Control for Working Machinery (AI4Machinery)

Rauno Heikkilä

University of Oulu, Civil Engineering, Finland

Background

- Rapid advancement of AI and robotics impacting construction, forestry, and mining sectors
- AI integration in autonomous control systems enhances efficiency, safety, and sustainability
- Several research institutions and companies and contributing to AI in heavy machinery: PWRI, University of Tokyo, Brightwayvision, Hydack, ETH Zurich, Deepx,...
- AI4Machinery consortium background: Technion, Normet, Novatron, Infrakit, Destia, PictM, Nokia, VTT, University of Oulu

SWARM Oulu – Our Current Machines



Bobcat E85
8 tn



CAT D6K2
(2016)
14 tn



Bomag
BW177BVC-5
with Vario
Control System

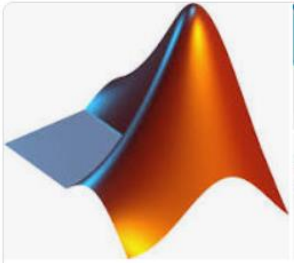


Electric Autonomous Truck,
later several trucks



Drones for surveying,
monitoring, video capturing for
remote control,...

Matlab/ Simulink



ROS

Trajectories



ROS



SIMlabIO
(CAN bus-
Matlab/
Simulink
interface)

CAN bus



ECU

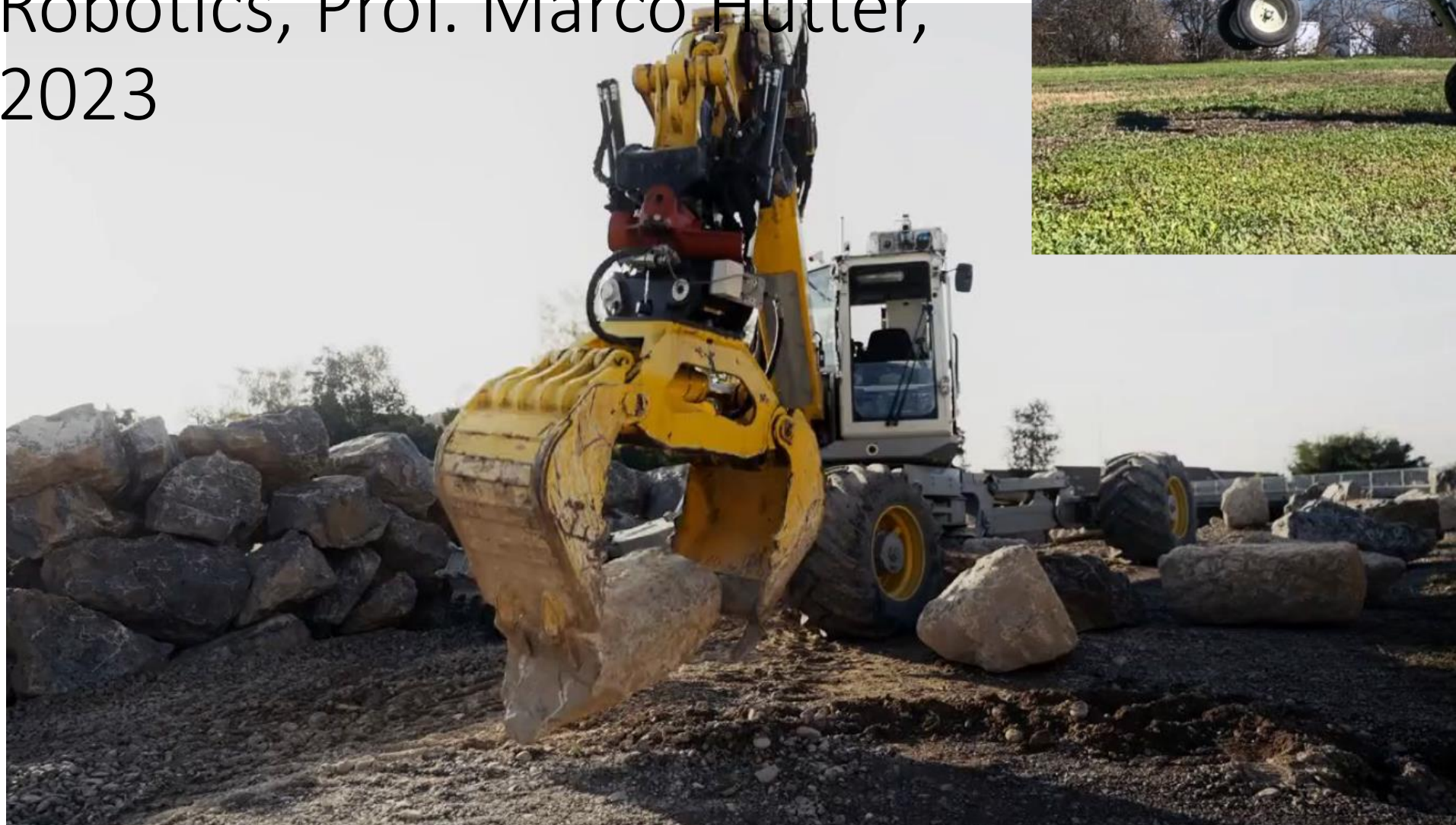


BIM –
Building
information
models



Software Platform Used

AI is better Operator - Case ETH Zurich & Gravis Robotics, Prof. Marco Hutter, 2023



Example, Neural Network controlled Autonomous Excavation, 5/2024

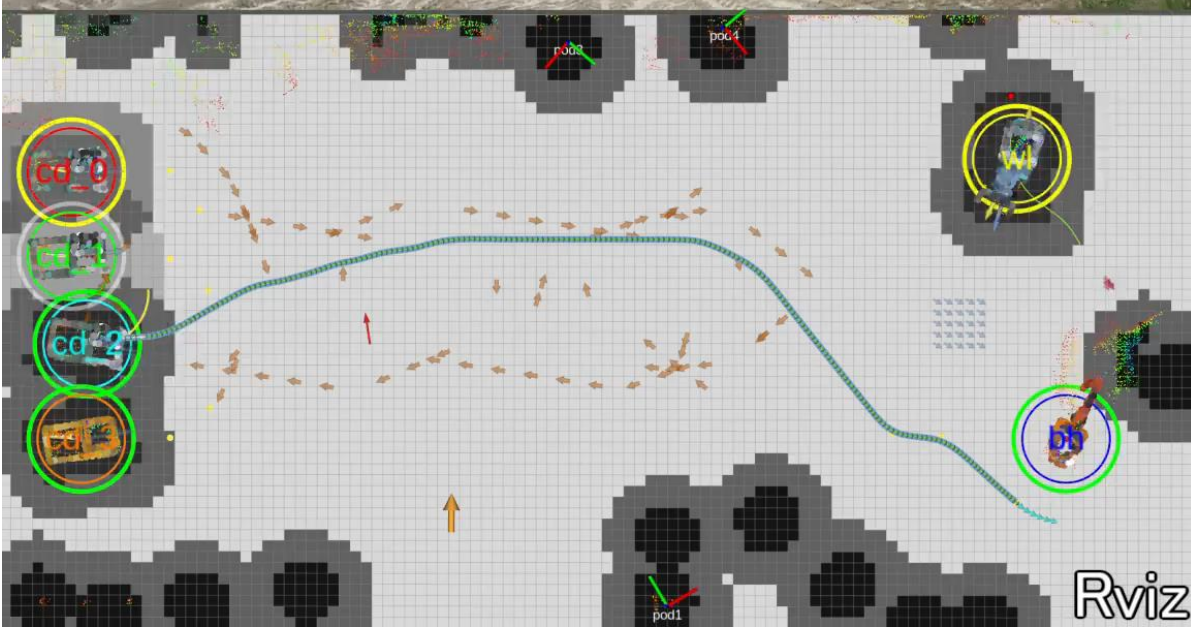


Neural network control demonstration at PWRI test field in Tsukuba, Japan, 2023

3x speed

Camera





Rviz

		soil	
		team_0@wl	team_1@bh
		3.60	2.40
status		team	
CD0	stand-by	0.00	team_0
CD1	stand-by	0.00	
CD2	move	0.00	team_1
CD3	stand-by	0.00	team_1

cd 0

cd 2

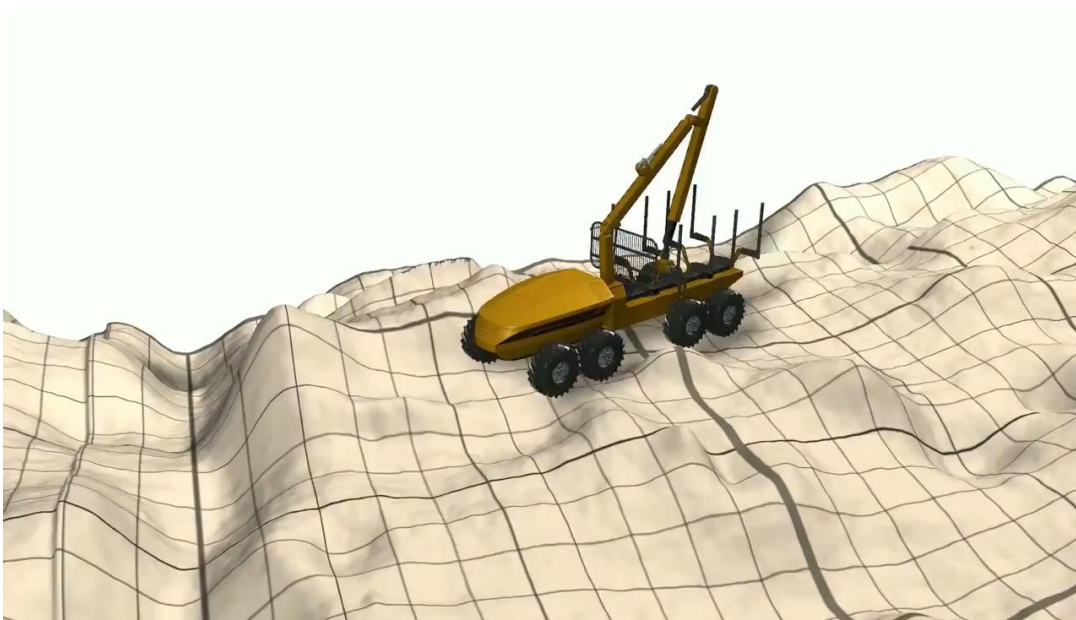
wl_team

bh_team

Aim

- Research and develop AI-powered autonomous control for work machines and swarms
- Revolutionize AI use in industrial working machinery for efficiency, safety, and sustainability
- AI4Machinery consortium aims:
 - Technion, Normet, Novatron, Infrakit, Destia, Nokia,
 - University of Oulu
 - VTT

Workpackages and Tasks



- 1 BACKGROUND
- 2 AIM
 - 2.1 Research aims of the public research part
 - 2.2 Research objectives of companies
- 3 WORKPACKAGES AND TASKS
 - WP1: Coordination
 - WP1.1 Project planning
 - WP1.2 Project control
 - WP2: AI for automation modules, networks and data intelligence
 - WP2.1 AI-assisted sensing, mapping and localization
 - WP2.2 Perception and data collection in harsh environment
 - WP2.3 Wireless information communication and industrial metaverse
 - WP2.4 AI for machine control modules and systems
 - WP2.5 Site and task planning and control, simulation and AI teaching
 - WP2.6 AI for model based infra construction process
 - WP3: AI for Autonomous Machines
 - WP3.1 AI assisted teleoperation
 - WP3.2 AI powered autonomous operations
 - WP3.3 Work safety and cybersecurity
 - WP4: AI for Autonomous Swarms
 - WP4.1 Open platform for swarm
 - WP4.2 AI powered autonomous machine swarm
 - WP4.3 AI powered drone swarm
 - WP4.4 International Standardization of Solutions
 - WP5: Demonstrations and pilots
 - WP5.1 Infra Construction - AI powered Autonomous Infra Construction machines and Swarm
 - WP5.2 Forestry – AI powered Autonomous Forest machines and Swarm
 - WP5.3 Mining – AI powered Autonomous breaker and Swarm
 - WP6: International cooperation and business network (growth engine)
 - WP7: Exploitation and publication
- 4 RESOURCES
 - 4.1 Participating organizations and key personnel
 - 4.2 Schedule
 - 4.3 Costs
 - 4.4 Funding plan
- 5 BUSINESS POTENTIALS AND RISKS

Resources

- Research consortium: Technion (Maria Kivinen), Normet (Santeri Lampinen), Novatron (Antti Kolu), Infrakit (Visa Hokkanen), Destia (Mika Jaakkola), Nokia (Jarkko Pellikka), University of Oulu (Rauno Heikkilä), VTT (Tapio Heikkilä)
- International research cooperation and exchanges:
 - PWRI, Tsukuba, Japan
 - Tokyo University, Japan
 - ETH Zurich, Switzerland
 - University of Nebraska at Lincoln, Omaha site, USA
- Other international cooperation
 - European Robotics Forum
 - IAARC/ISARC

Resources

- Schedule plan: 1.10.2024-31.3.2027 (duration approximately 2.5 years)
- Cost estimate (draft):
 - Company research part 5 285 423 eur
 - Public research part 3 030 663 eur
 - Total 8 316 086 eur
- Funding plan (draft):
 - Consortium partners 3 238 129 eur
 - Business Finland 5 078 857 eur
 - Total 8 316 086 eur

Business Potentials and Risks

- Based on the industrial consortium partners:
 - Technion
 - Normet
 - Novatron
 - Infrakit
 - Destia
 - Nokia